

Intercomparison of water leaving radiances from ocean color sensors using *in situ* measurements



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IVOS Workshop – Noordwijk, October 12-14, 2004

Overview on:

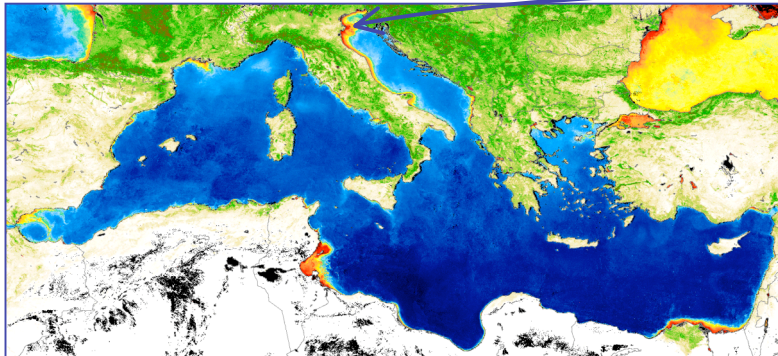
- The CoASTS ocean color cal/val program
- Uncertainties in the *in situ* optical measurements
- Space derived versus *in situ* normalized water leaving radiances

Coastal Atmosphere and Sea Time Series (CoASTS)

- Objectives:**
1. Monthly data collection at the Acqua Alta Oceanographic Tower (AAOT)
 2. Data exploitation in ocean color products development and validation.

Time frame: July 1995 – September 2005

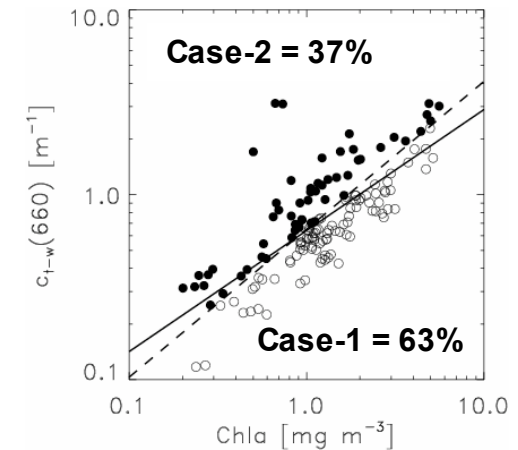
The AAOT site (45.31 N, 12.50 E)



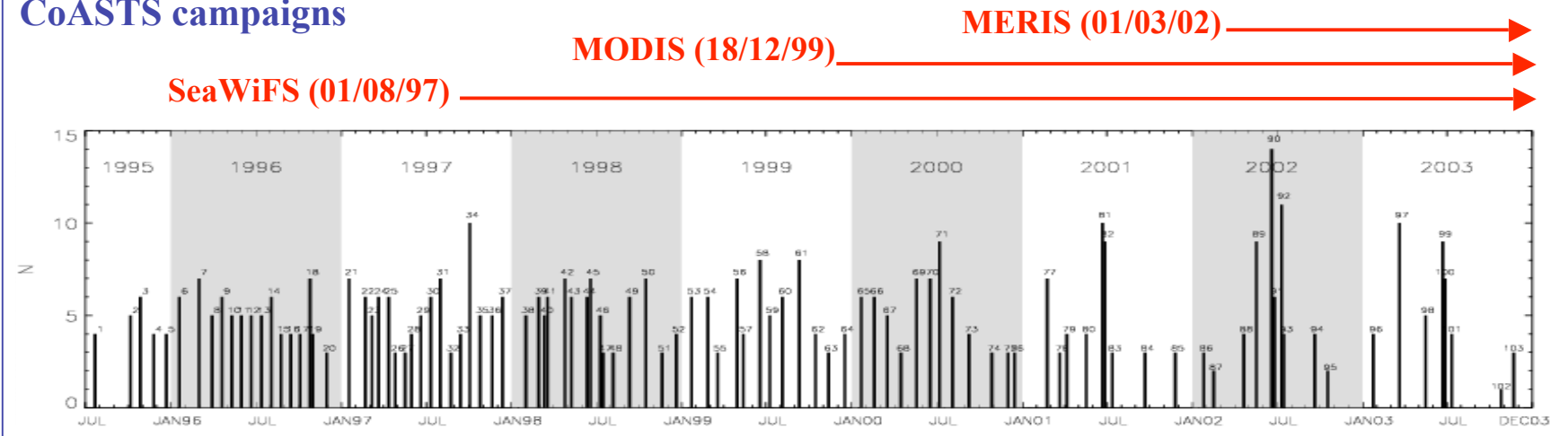
Monthly Chla composite from SeaWiFS imagery (September 1998)



AAOT



CoASTS campaigns



CoASTS measurements

Field measurements

- Profiles of $L_u(z, \lambda)$, $E_u(z, \lambda)$, and $E_d(z, \lambda)$
- Profiles of $c(z, \lambda)$ and $a(z, \lambda)$ (from 01/97)
- Profiles of $b_b(z, \lambda)$ (from 04/00)
- $E_d(0^+, \lambda)$ and $E_i(0^+, \lambda)$
- $E_s(0^+, \lambda)$ and $L_i(0^+, \theta, \phi, \lambda)$
- $L_w(40^\circ, 90^\circ, \lambda)$ (from 04/02)
- Ancillary ($T_w(z)$, $S_w(z)$, P_a , RH , T_a , W_s , W_d , C , M)

Laboratory measurements

(from water samples at 3 depths)

- **Pigments (HPLC)**
- $a_{ph}(\lambda)$ and $a_{dp}(\lambda)$
- $a_{ys}(\lambda)$
- **TSM**
- Ancillary (**PSD**) (up to 10/98)

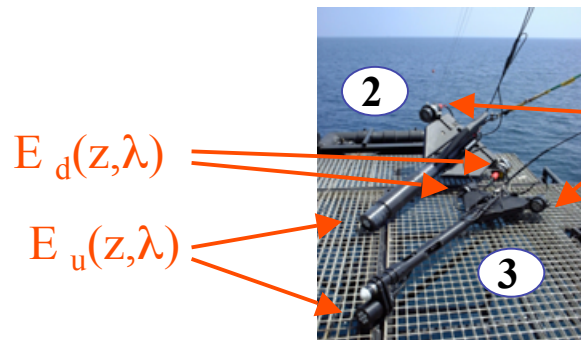
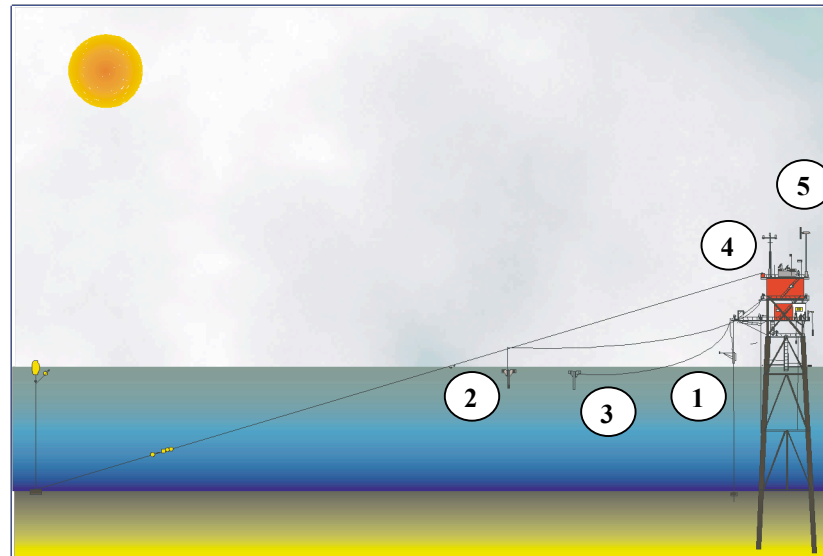
G.Zibordi J.F.Berthon, J.P.Doyle, S.Grossi, D. van der Linde, C.Targa, L.Alberotanza. *Coastal Atmosphere and Sea Time Series (CoASTS), Part 1: A long-term measurement program*. NASA TM-2002-206892, vol. 19, S.B.Hooker and E.R.Firestone, Eds., NASA Goddard Space Flight Center, Greenbelt, Maryland, 2002, 29 pp.

AAOT Optical Systems

$E_d(0^+, \lambda), E_i(0^+, \lambda)$



$E_s(\lambda), L_i(\theta, \phi, \lambda), L_w(\lambda)$

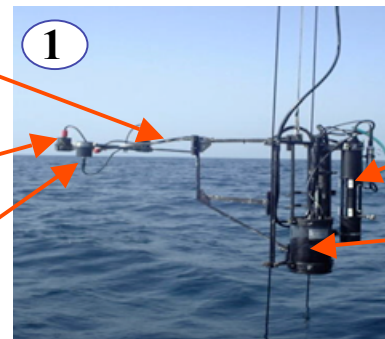


$L_u(z, \lambda)$

$L_u(z, \lambda)$

$E_u(z, \lambda)$

$E_d(z, \lambda)$

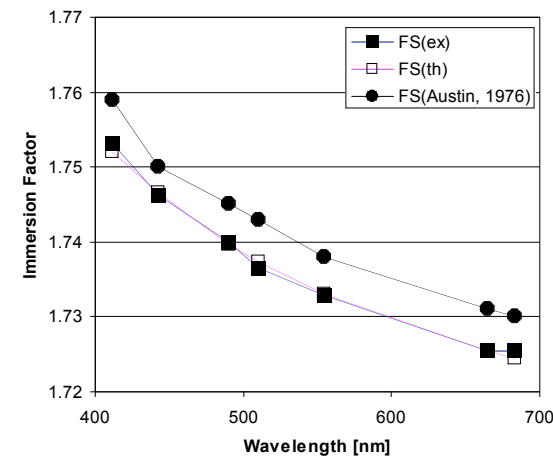
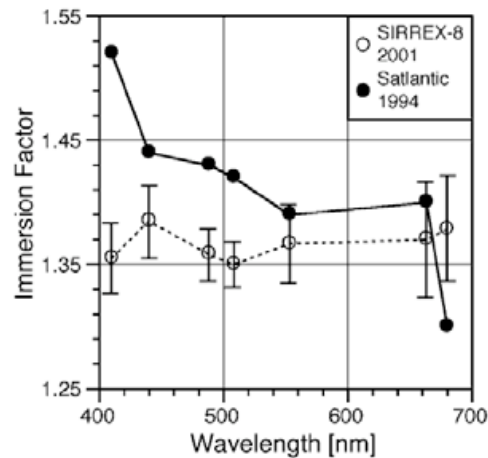
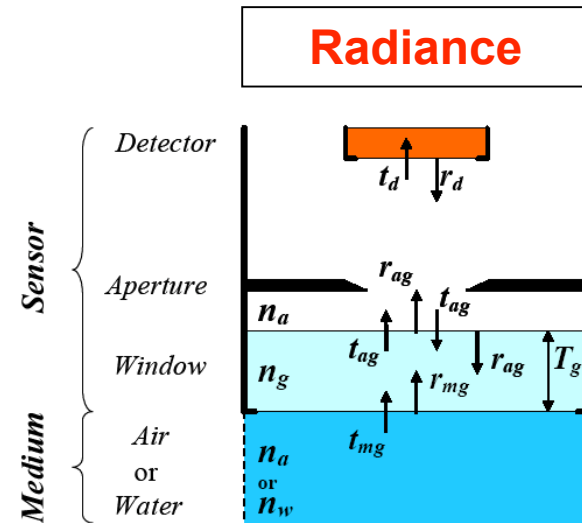
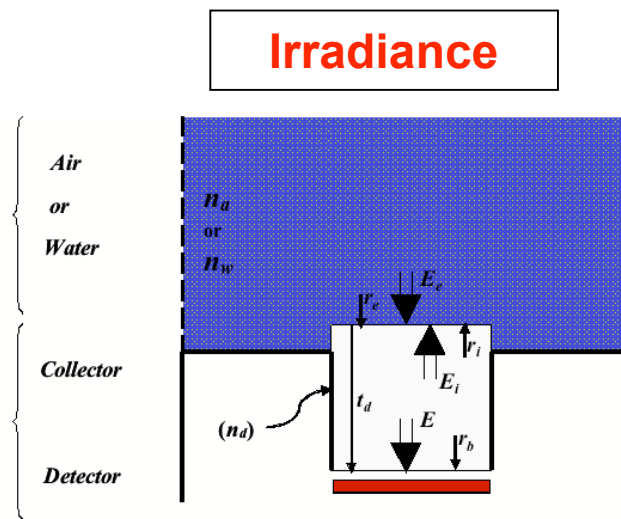


$a(z, \lambda)$

$c(z, \lambda)$

$b_b(z, \lambda)$

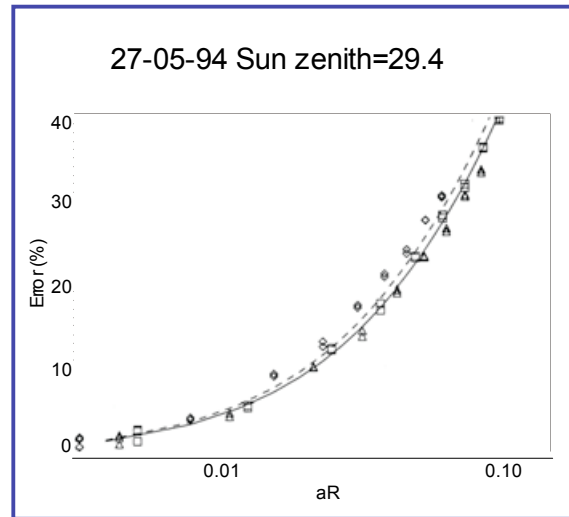
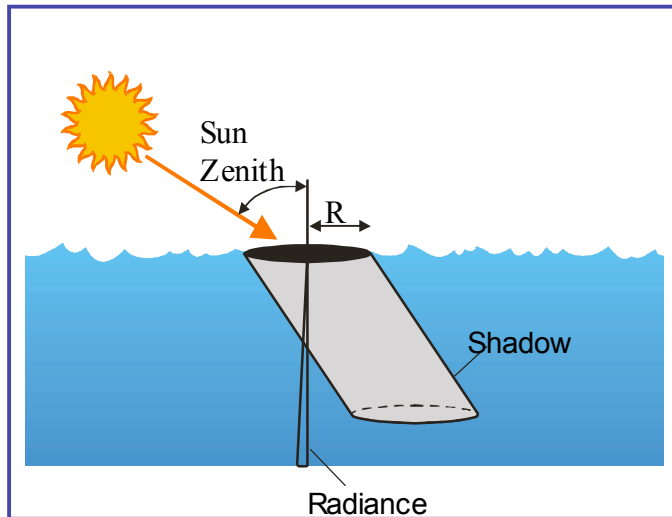
Immersion effects for in-water radiometers



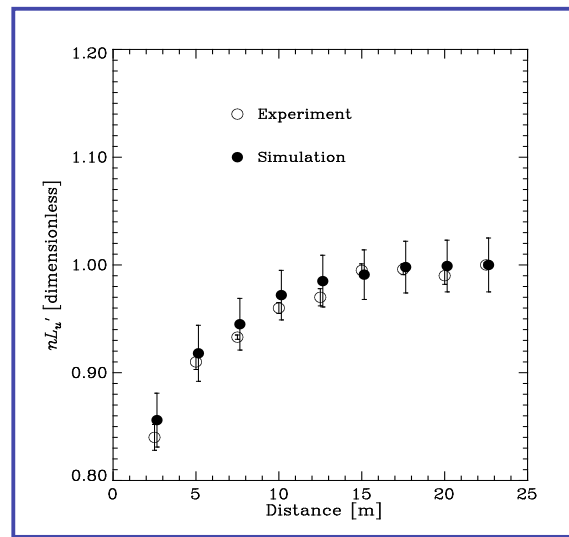
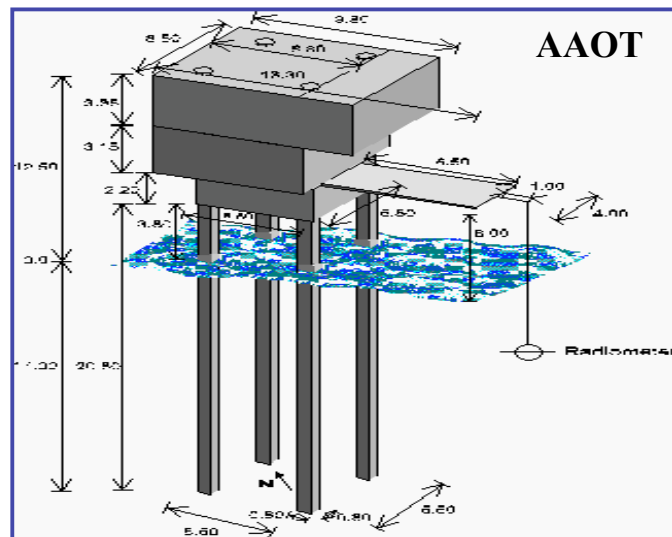
G.Zibordi, S.Hooker, J.Mueller, S.McLean, G.Lazin. Characterization of the immersion coefficient of a class of underwater irradiance sensors. *Journal of Atmospheric and Oceanic Technology*, 21:501-514, 2004.

G.Zibordi. Immersion coefficient of in-water radiance instruments: an experimental assessment. *Journal of Atmospheric and Oceanic Technology* (submitted), 2004.

Measurement Uncertainties

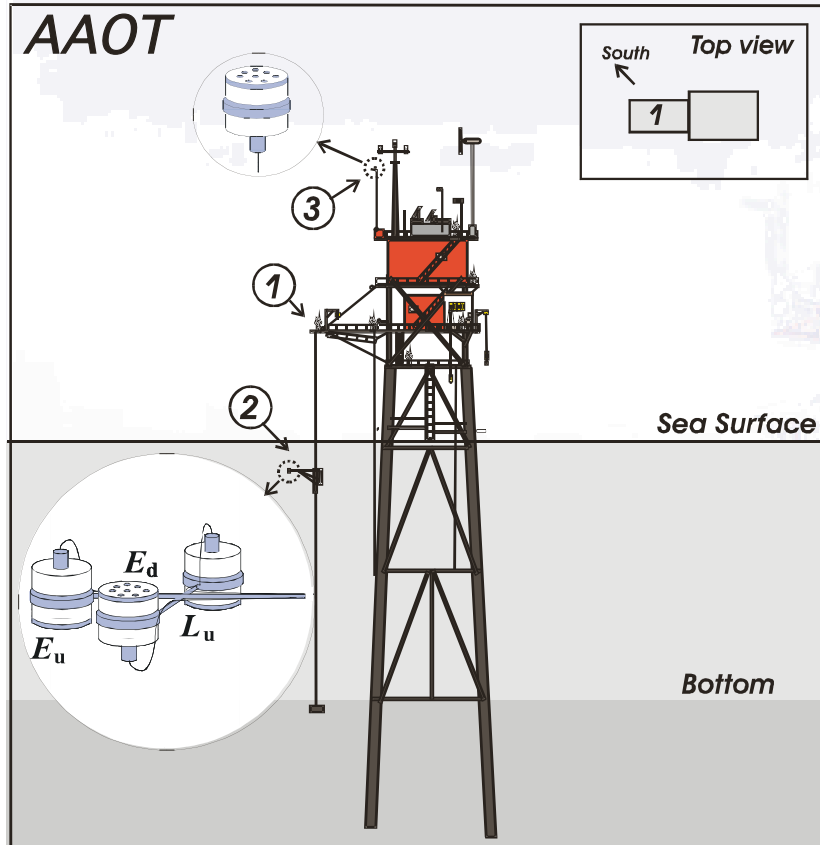


G.Zibordi and G.M.Ferrari,
Instrument self shading in
underwater optical meas-
urements: experimental data.
Applied Optics, 34: 2750-2754,
1995.



J.P.Doyle & G.Zibordi. Optical propagation within a 3-dimensional shadowed atmosphere/ocean field: application to large deployment structures. *Applied Optics*, 41:4283-4306, 2002.

In water radiometry

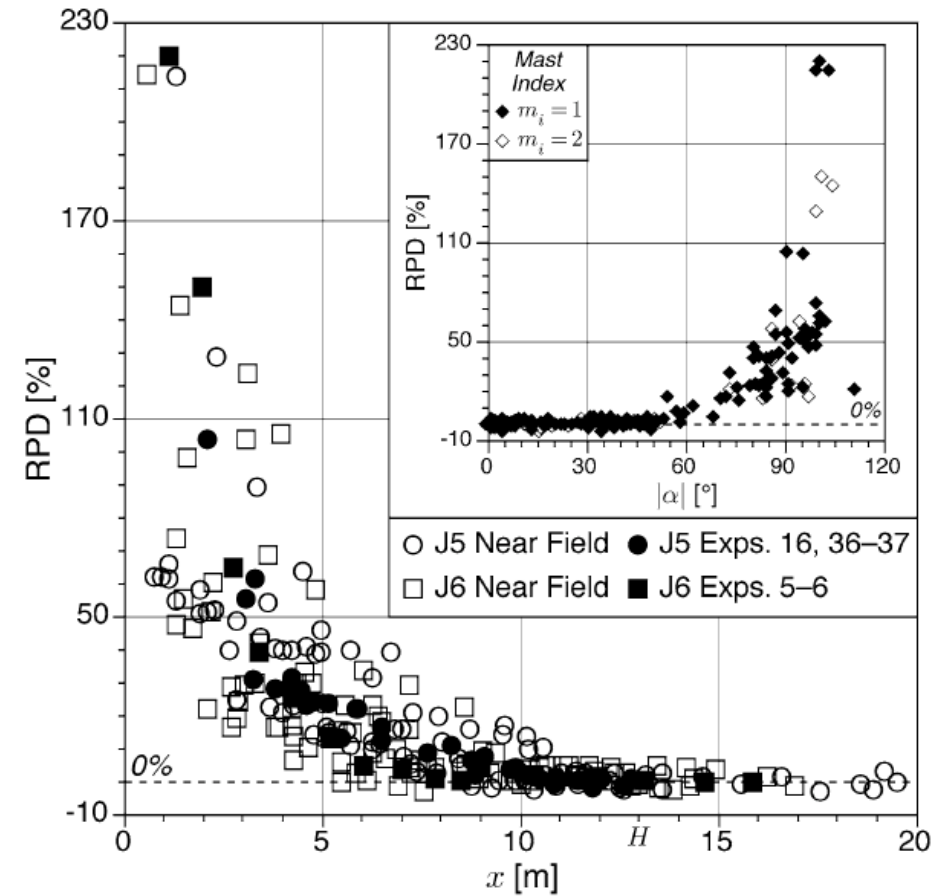
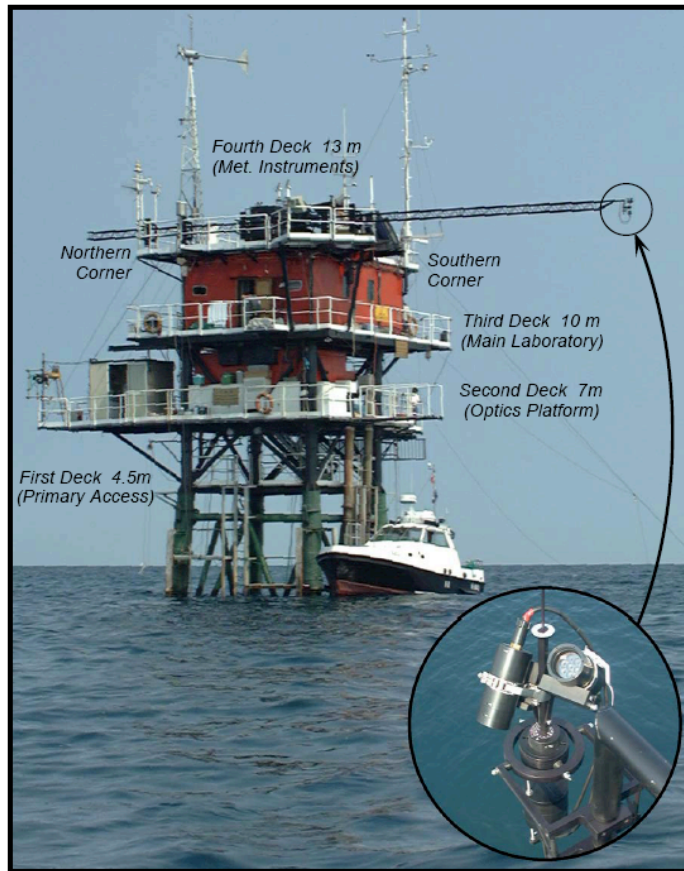


| | | | | | | |
|-------------------------|-----|-----|-----|-----|-----|-----|
| Uncertainties (L_u) | 412 | 443 | 490 | 510 | 555 | 665 |
| Abs. calibration [1] | 2.4 | 2.3 | 2.3 | 2.4 | 2.4 | 2.3 |
| Residual shad. pert. | 2.5 | 2.1 | 1.7 | 1.6 | 1.7 | 3.0 |
| Environ. effects | 3.0 | 3.0 | 3.1 | 3.1 | 3.1 | 3.1 |
| Quadrature sum | 4.6 | 4.3 | 4.2 | 4.2 | 4.3 | 4.9 |

[1] Including the calibration source accuracy, I_f accuracy and instrument stability

G.Zibordi, F. Mélin, S. B. Hooker, D. D'Alimonte and B. Holben. *An autonomous above-water system for the validation of ocean color radiance data. IEEE Transactions in Geoscience and Remote Sensing* (accepted), 2003.

Perturbations in above-water radiance measurements

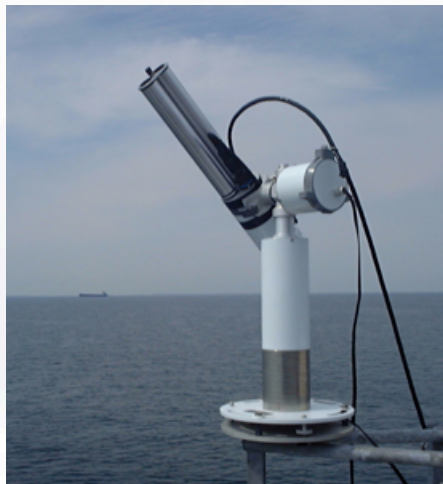


S. B. Hooker and G. Zibordi. *Platform Perturbations in above-water radiometry*. *Applied Optics*, Revised on June 2004.

Above water radiometry



CE-318 (sea-viewing)



CE-318 (sky-viewing)

$$L_W^{SP}(\varphi, \theta, \lambda) = L_T(\varphi, \theta, \lambda) - \rho(\varphi, \theta, \theta_0, W) L_i(\varphi, \theta', \lambda)$$

$$(\varphi = \varphi_0 + 90^\circ; \theta = 40^\circ; \theta' = 140^\circ)$$

| Major uncertainties (L _w) | 412 | 440 | 500 | 555 | 670 |
|---|-----|-----|-----|-----|------|
| Absolute calibration ^[1] | 2.2 | 2.1 | 2.1 | 2.1 | 2.1 |
| Viewing angle correction ^[2] | 1.0 | 1.0 | 1.6 | 1.8 | 0.9 |
| Environmental perturbations | 4.0 | 3.7 | 3.1 | 3.0 | 12.0 |
| Quadrature sum | 4.7 | 4.4 | 4.1 | 4.1 | 12.2 |

^[1] Including the calibration source accuracy and instrument stability

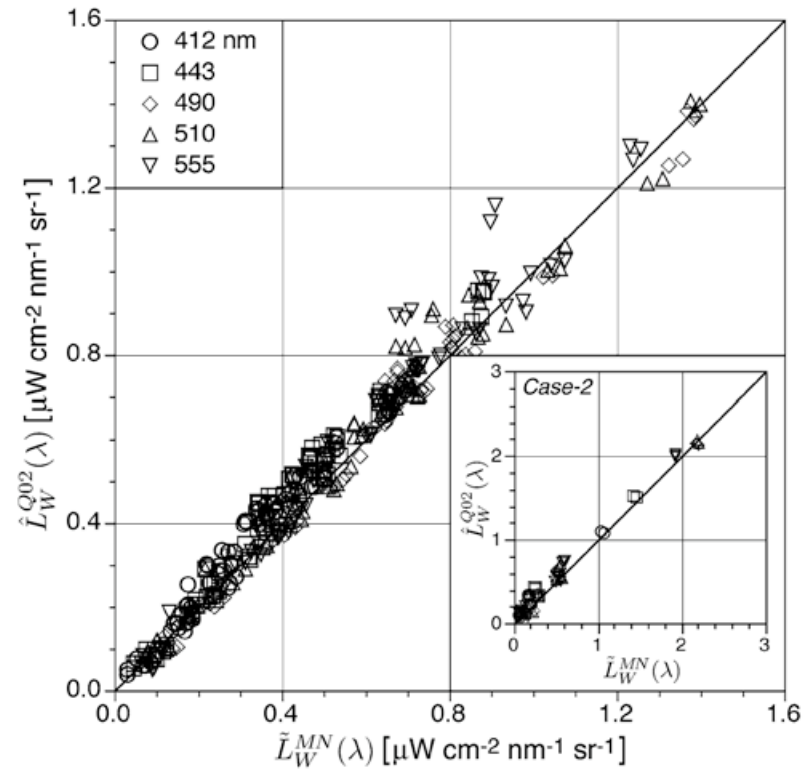
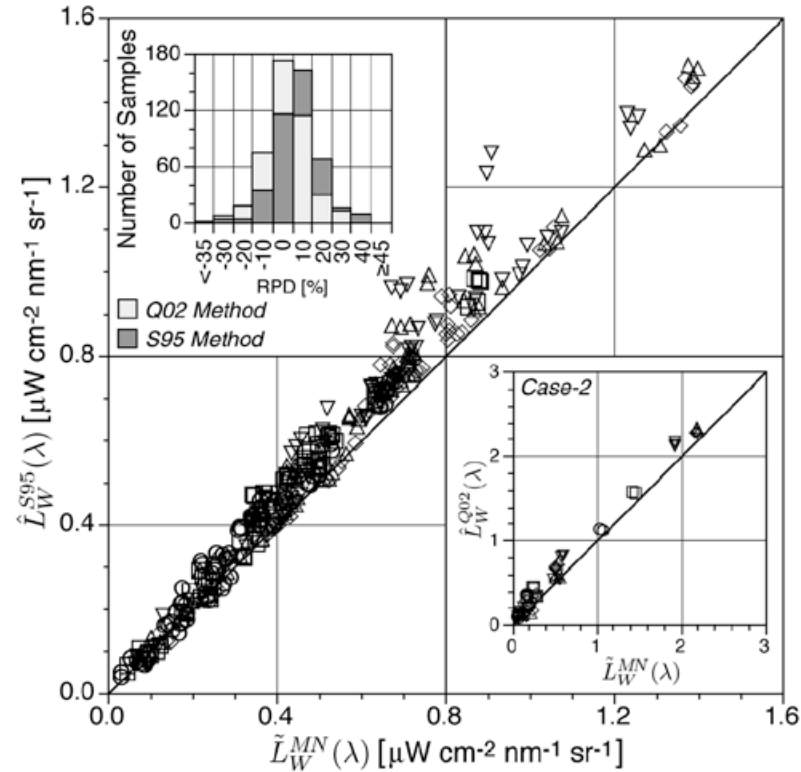
^[2] Assuming an arbitrary 25% in the applied correction

G.Zibordi, F. Mélin, S. B. Hooker, D. D'Alimonte and B. Holben. *An autonomous above-water system for the validation of ocean color radiance data. IEEE Transactions in Geoscience and Remote Sensing* , 42:401-415, 2004 .

S.B.Hooker, G.Zibordi, D. van der Linde, D.D'Alimonte, J.F.Berthon and J.Brown. *Tower perturbation measurements in above-water radiometry.* NASA TM 2002-206892, v. 23
S.B.Hooker and E.R.Firestone, Eds., NASA Goddard Space Flight Center, Greenbelt, Maryland, 2003, 35 pp.

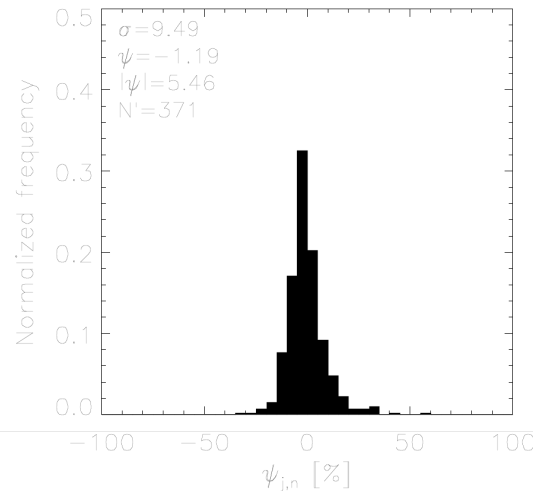
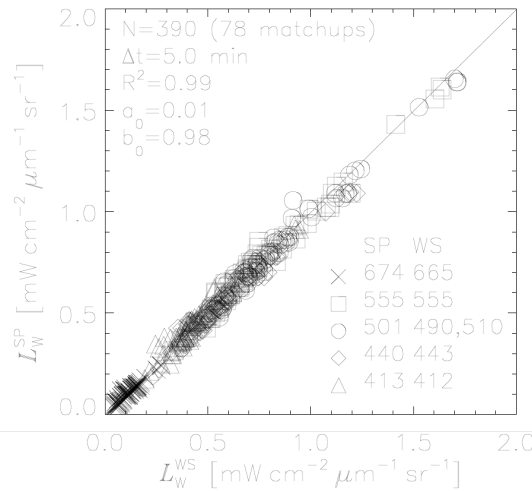
Above- versus in-water

$$L_W^{S95}(\varphi, \theta, \lambda) = L_T(\varphi, \theta, \lambda) - \rho(\varphi, \theta, \theta_0, W) L_i(\varphi, \theta', \lambda) \quad L_W^{Q02}(\lambda) = L_W^{S95}(\varphi, \theta, \lambda) C_{RQ}(\lambda, \theta, \varphi, \theta_0, \tau_a, Chla, W)$$



S.B.Hooker, G.Zibordi, J.-F.Berthon and J.Brown. *Above water radiometry in shallow coastal waters*, Applied Optics 21:4254-4268, 2004.

Above- versus in-water



Water Leaving Radiance

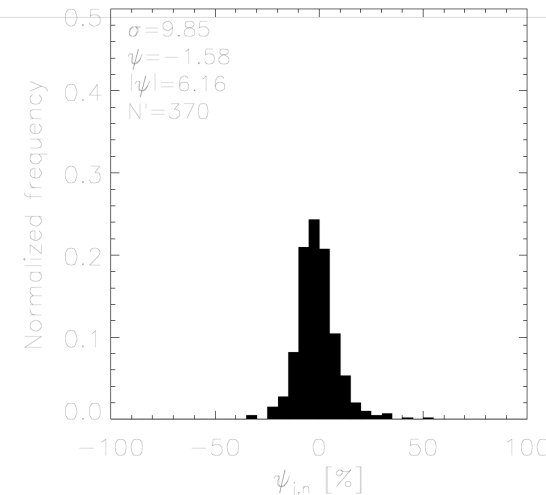
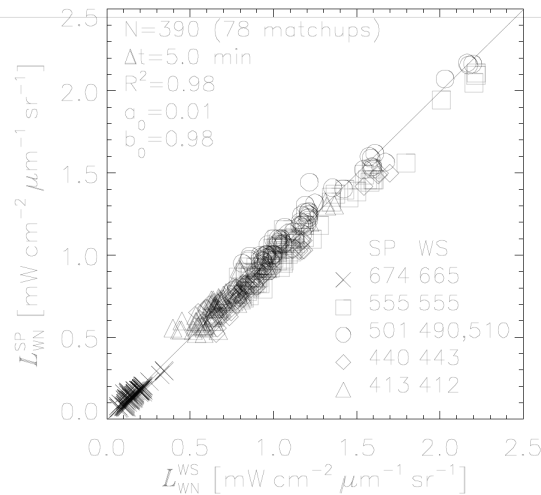
SeaPRISM

$$L_W^{SP}(\varphi, \theta, \lambda) = L_T(\varphi, \theta, \lambda) - \rho(\varphi, \theta, \theta_0, W) L_i(\varphi, \theta', \lambda)$$

$$L_W^{SP}(\lambda) = L_W^{SP}(\varphi, \theta, \lambda) C_{f/Q}(\lambda, \theta, \varphi, \theta_0, \tau_a, Chla, W)$$

WiSPER

$$L_W^{WS}(\lambda) = 0.54 L_u^{WS}(0^-, \lambda)$$



Normalized Water Leaving Radiance

SeaPRISM

$$L_{WN}^{SP}(\lambda) = L_W^{SP}(\lambda) C_{f/Q}(\lambda, \theta_0, \tau_A, Chla) (D^2 t_d(\lambda) \cos \theta_0)^{-1}$$

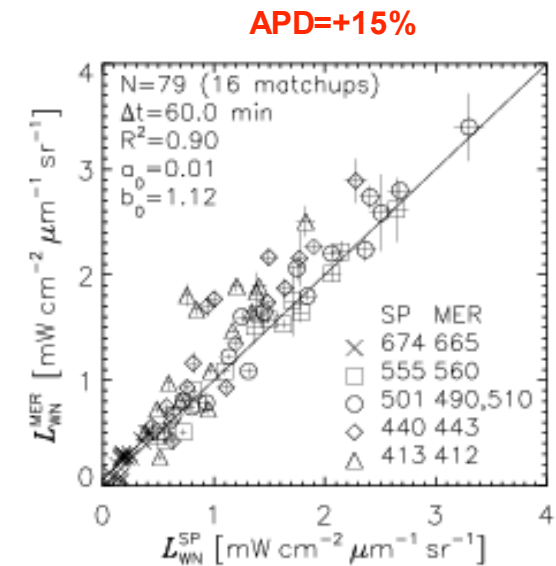
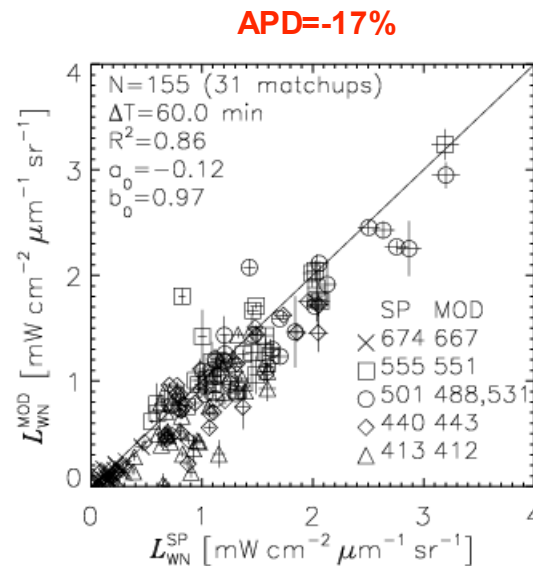
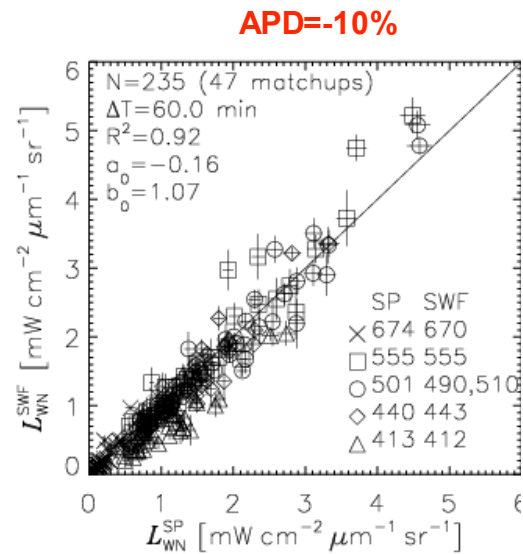
WiSPER

$$L_{WN}^{WS}(\lambda) = L_W^{WS}(\lambda) \frac{E_0(\lambda)}{E_d(0^+, \lambda)} C_{f/Q}(\lambda, \theta_0, \tau, Chla)$$

G.Zibordi, F. Mélin, S. B. Hooker, D. D'Alimonte and B. Holben. *An autonomous above-water system for the validation of ocean color radiance data. IEEE Transactions in Geoscience and Remote Sensing*, 42:401-415, 2004 .

Ocean Color Sensors Intercomparison

AAOT, May 2002-May 2003, 3X3 pixels, $\theta < 56^\circ$, $\theta_0 < 70^\circ$, $\Delta T = 60$ min; $L_{WN} > 0$



G.Zibordi, F. Mélin, S. B. Hooker, D. D'Alimonte and B. Holben. An autonomous above-water system for the validation of ocean color radiance data. *IEEE Transactions in Geoscience and Remote Sensing* , 42:401-415, 2004 .

SeaWiFS vicarious calibration exercises

(June 2002-May 2003 data)

Vicarious correction coefficients at the AAOT site (SeaPRISM data)

| Band | Coefficient | StdDev |
|------|-------------|--------|
| 412 | 1.031 | 0.010 |
| 443 | 1.005 | 0.011 |
| 555 | 0.998 | 0.020 |
| 670 | 0.977 | 0.019 |

Vicarious correction coefficients at the AAOT site (Moby data)

| Band | Coefficient |
|------|-------------|
| 412 | 1.013 |
| 443 | 0.996 |
| 555 | 0.991 |
| 670 | 0.956 |

Processed by Sean Bailey – SeaWiFS Project



EUROPEAN COMMISSION
JOINT RESEARCH CENTRE

Recommendations

- Establishment of in situ measurement sites providing quality assured data for the vicarious calibration of space sensors and the validation of derived products.
- Co-ordination among different sites for the standardization of measurement protocols.
- Creation of time-series of quality assured in situ measurements for the evaluation of long term satellite performances.