

Using MERIS and MODIS for Land Cover Mapping in the Netherlands

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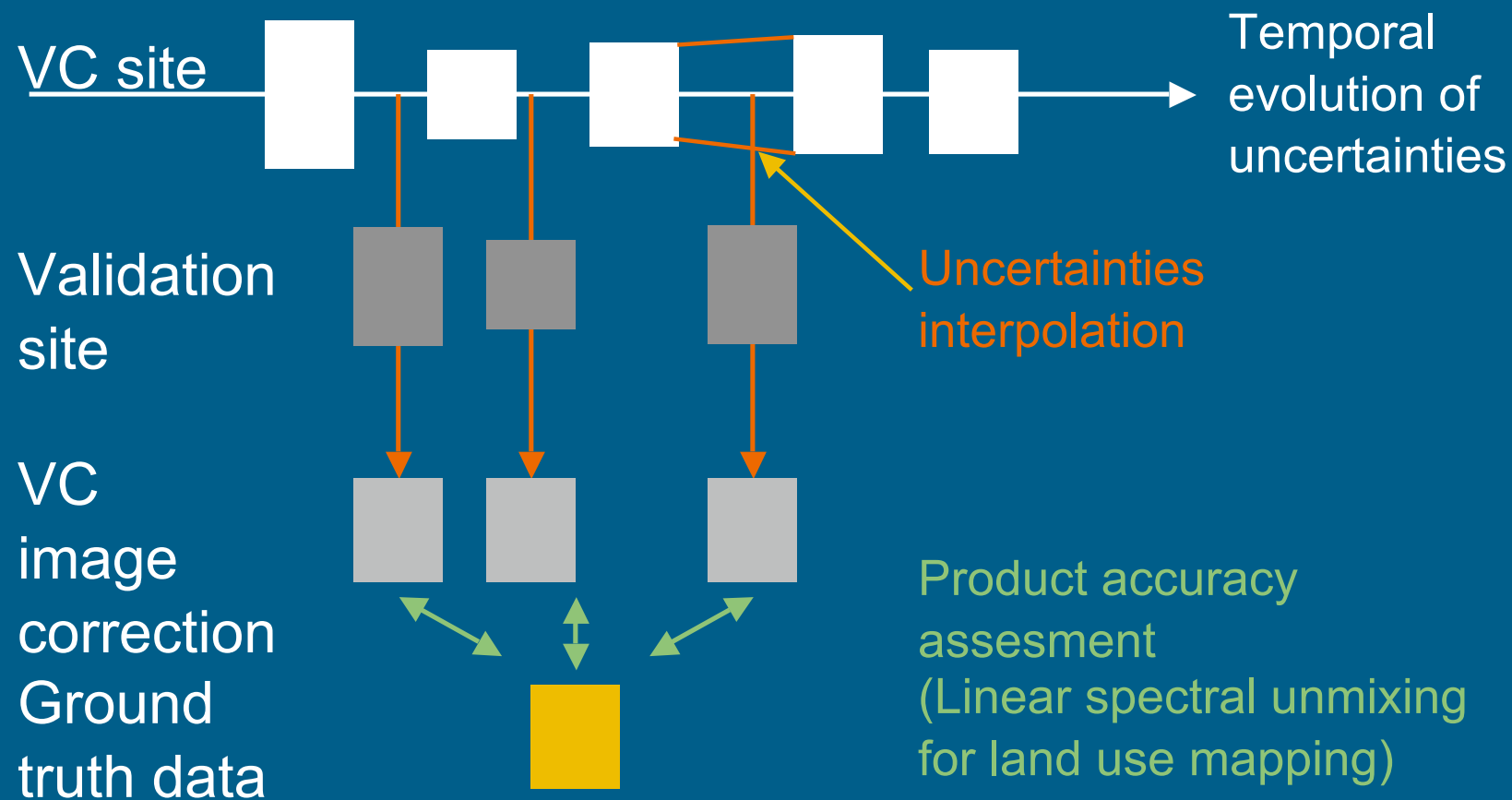
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Introduction

- Actual and reliable information on land use and land cover is needed both for agricultural and environmental applications.
- Medium resolution sensors can provide this information at a regional or global scale. They fill the gap between the low and the high spatial resolution sensors.



Introduction II



Objective

- Compare MERIS and MODIS for land use mapping
 - Study area: The Netherlands
 - Classifier: Linear Spectral Unmixing and Matched Filtering
 - Data type: Level 1b (Radiance)
 - Date: 14th July 2003
- Two study cases/comparisons
 - “Spatial resolution”
 - All medium resolution bands (<1km) will be used
 - Working scale will be 300m (resampling if necessary)
 - “Spectral resolution”
 - A similar spectral configuration will be studied



Basic Facts

	MERIS	MODIS
Organization	ESA	NASA
Primary Mission	Ocean color	Monitoring the Earth (Land Processes)
Swath	1150 Km	2230 km
Revisit Interval	2-3 days	1-2 days
Launch Date	March, 2002	Dec, 1999 (Terra) May, 2002 (Aqua)
Mission Duration	5-6 years	5-6 years

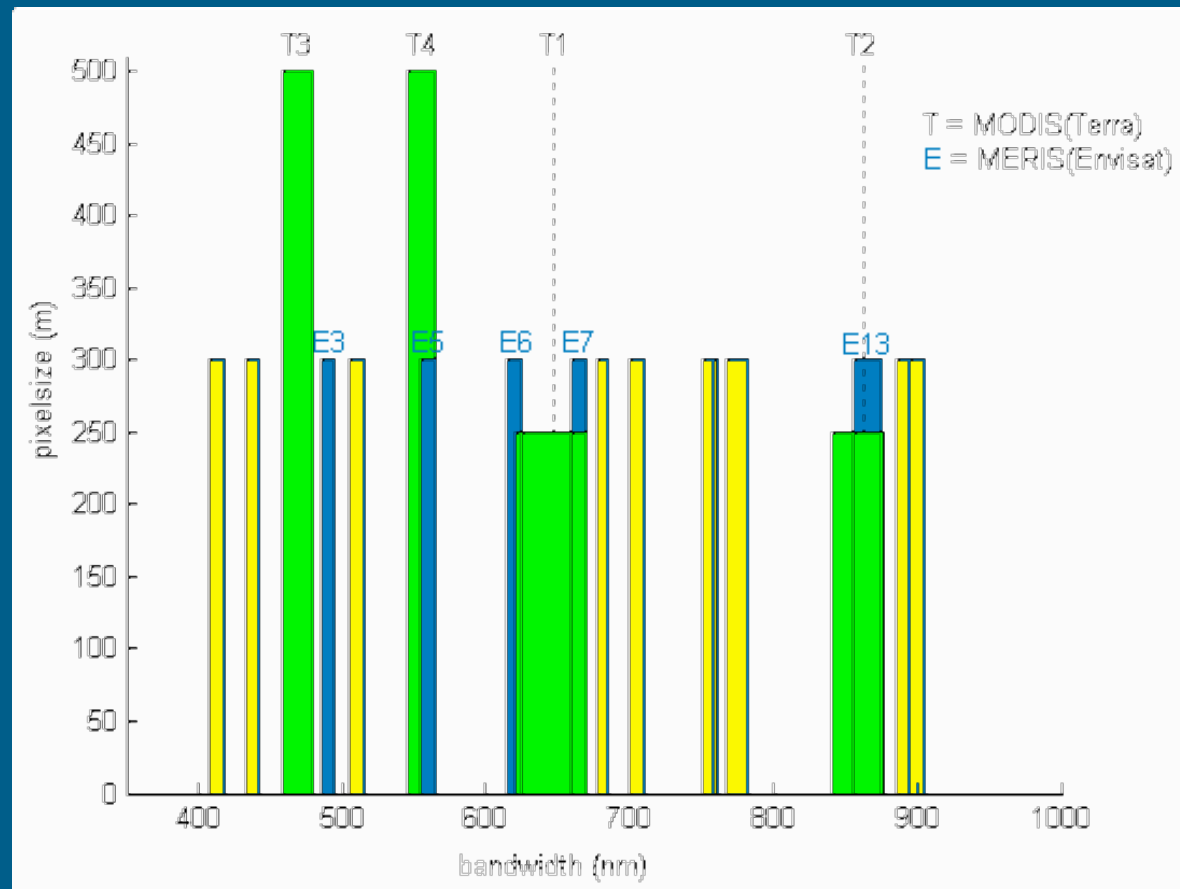
Basic Facts II & Study cases

MERIS	Center	Width	Pixel size
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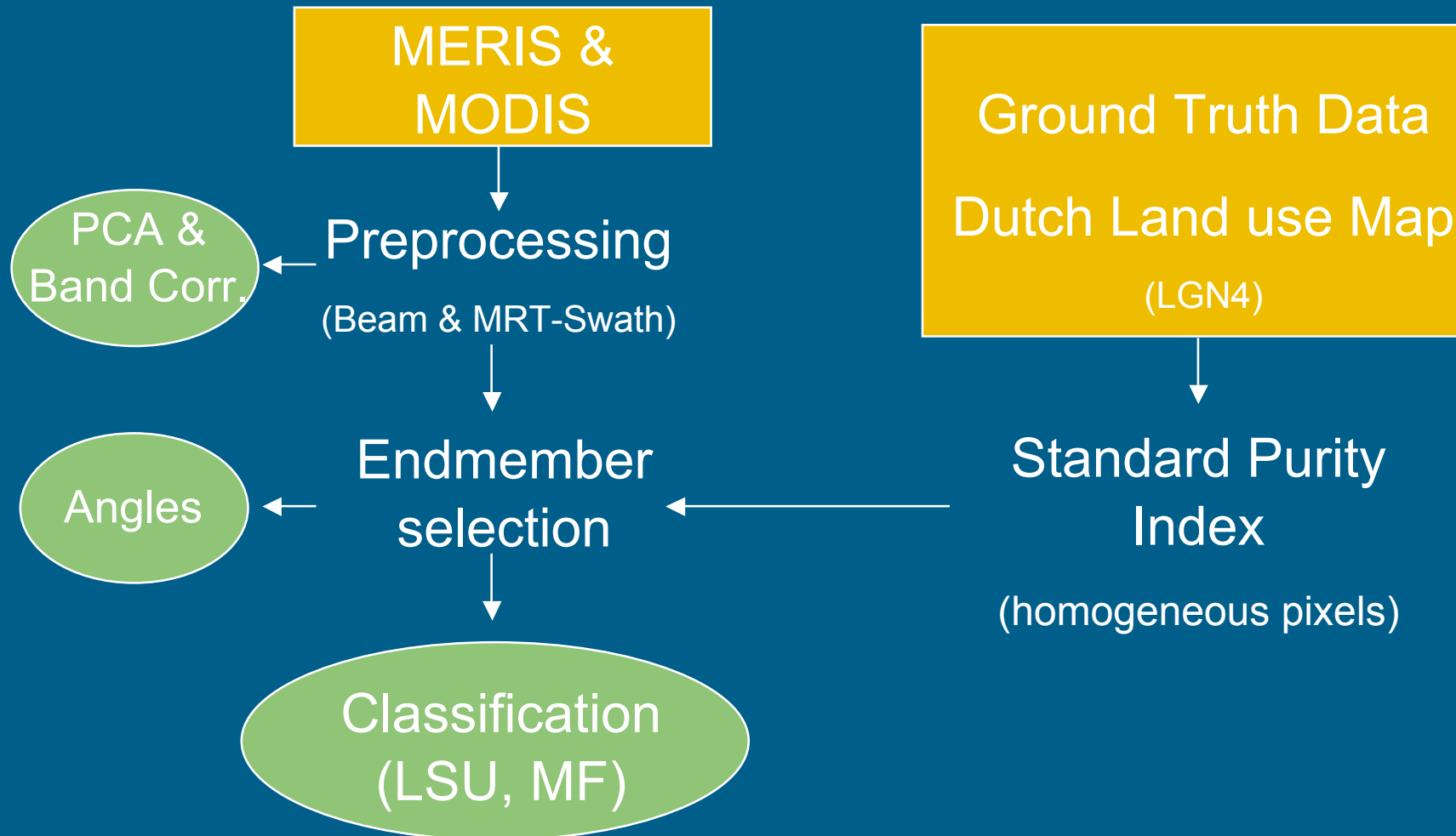
Band 3	490	10	300
Band 4	510	10	300
Band 5	560	10	300
Band 6	620	10	300
Band 7	665	10	300
Band 8	681.25	7.5	300
Band 9	705	10	300
Band 10	753.75	7.5	300

Band 12	775	15	300
Band 13	865	20	300
Band 14	890	10	300

MODIS	Center	Width	Pixel size
Band 1	645	50	250
Band 2	858.5	35	250
Band 3	469	20	500
Band 4	555	20	500
Band 5	1240	20	500
Band 6	1640	24	500
Band 7	2130	50	500



General Methodology



Preprocessing

- Geo-Coding and Radiance values

Using BEAM and MRT Swath the images were geo-referenced and the radiance values were computed after applying the respective gain factors.

- MODIS pixel size

250 → 300 m

500 → 300 m

- Corrections

MERIS Smile effect

MODIS Bow-Tie

- Image to Image registration

using the LGN as a reference both the MERIS and the MODIS image were co-registered to this dataset.

a 30 points, 3rd degree polynomial and NN transformation resulted in similar “errors”.

RMSE

MERIS 0.4347

MODIS 0.4406



MERIS



MODIS

July 14, 2003



PCA and Correlation Analysis

■ PCA

	MERIS	MODIS
PC1	90.80	89.08
PC2	8.70	8.19
PC3	0.28	1.79
Total	99.78	99.06

98% of PC1 is explained by the following bands:

MERIS 10,12,13 and 14 (NIR)

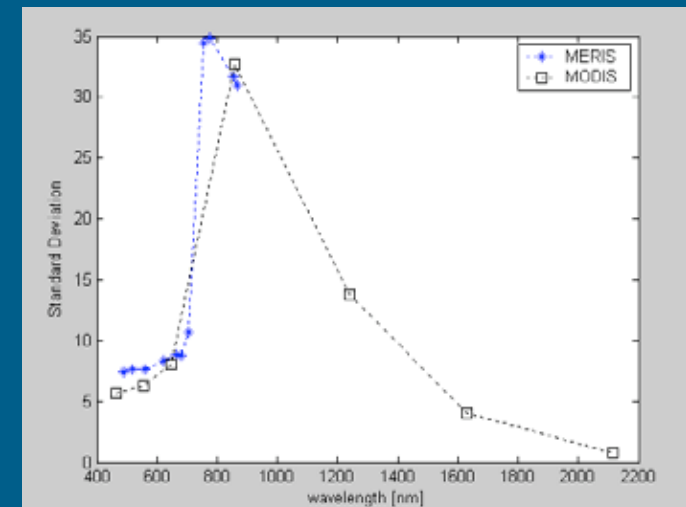
MODIS 2 and 5 (NIR)

■ Correlation Analysis

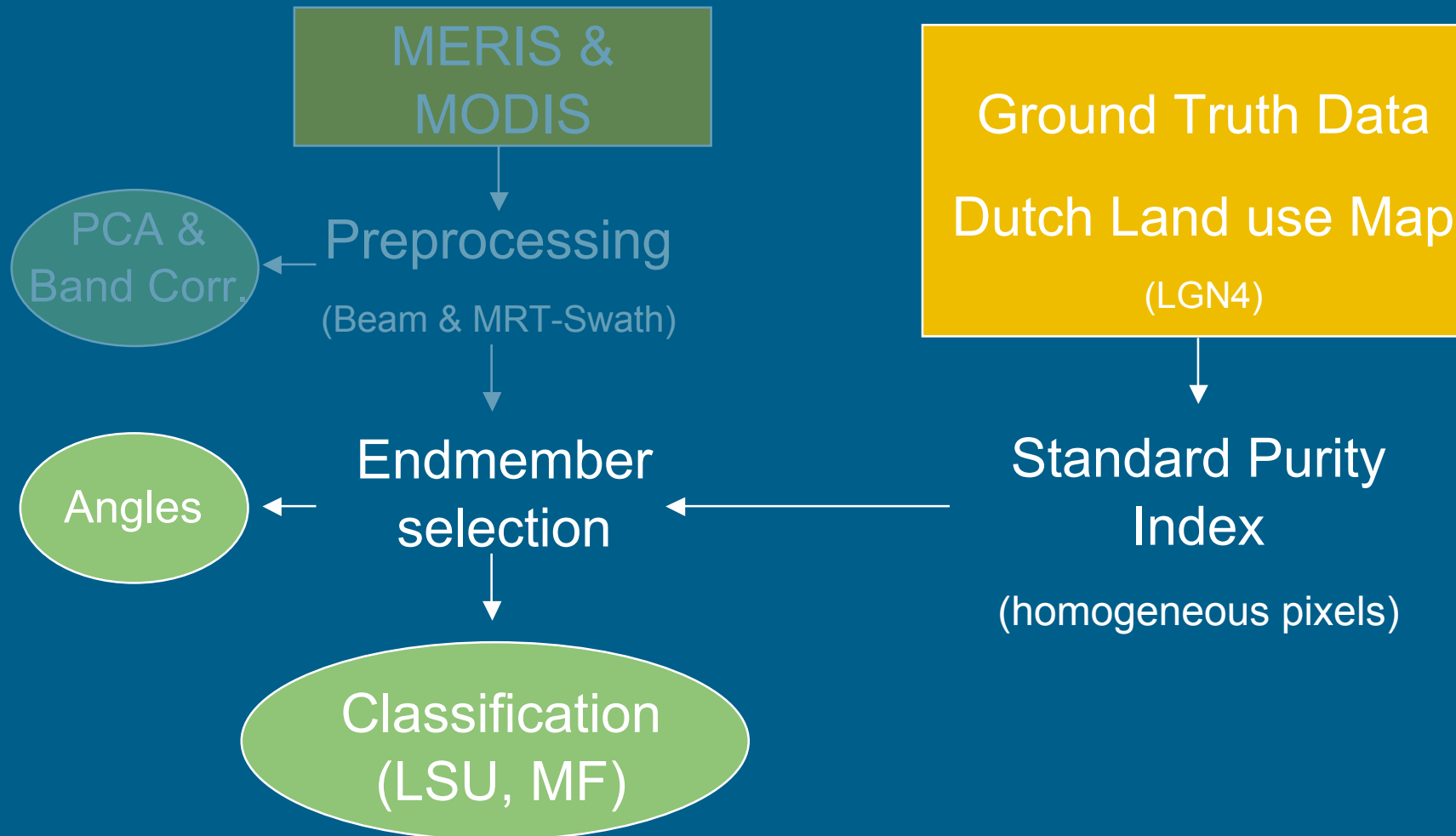
3 Groups can be identified for both sensors

MERIS: VIS (3:8), Red-Edge (9), NIR (10:14)

MODIS: VIS (1-3-4), NIR (2-5-6), SWIR (7)



General Methodology



LGN

■ Dutch Land Use Map

- Based on multitemporal classification of satellite imagery and integration with ancillary data.
- LGN4 was based on data from 1999 and 2000
- The overall accuracy is 85-90%
- “Spatial case”: aggregation to main 6 classes and 300m
- “Spectral case”: aggregation to main 4 classes and 300m

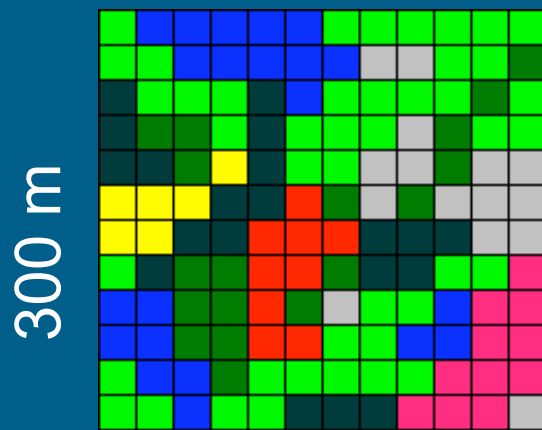


Land use	Cover [%]	Land use	Cover [%]
Grassland	39.92	Agriculture / Low vegetation	78.5
Arable land	24.37	Forest	9.40
Deciduous forest	2.92		
Coniferous forest	4.78	Water	<i>masked out</i>
Water	18.14		
Built up areas	9.87	Built up	12.05



Standard Purity Index

- The LGN4 was aggregated from 25 to 300m.
- During the aggregation the standard purity index (SPI) was computed

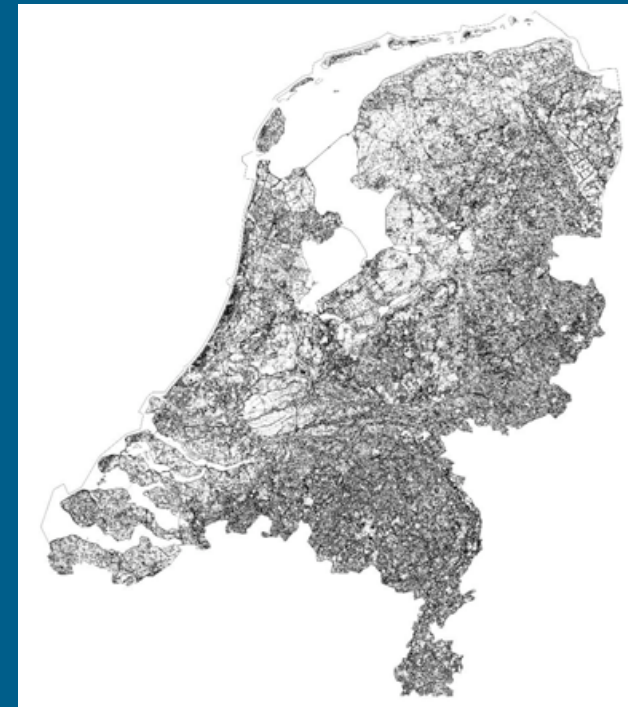


LGN 25 → 300 m

Majority filter
(12 x 12)

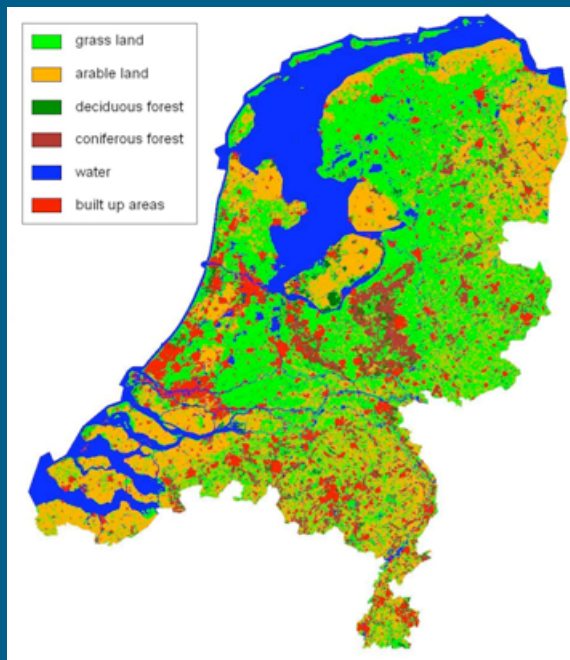
$$SPI = \sqrt{\frac{\sum_{i=1}^{i=n} (f_i - f_{\max class})^2}{n - 1}}$$

SPI MAP



Pure pixels 6 classes

- SPI>0.95 and a moving window filter of 3*3 (minimisation of adjacent effects) were used for the selection of the most homogenous pixels in The Netherlands



LGN 300m 6 classes



'Pure' Pixels



Pure pixels 4 classes

- The water was masked out since a low spectral confusion was expected with the rest of the classes



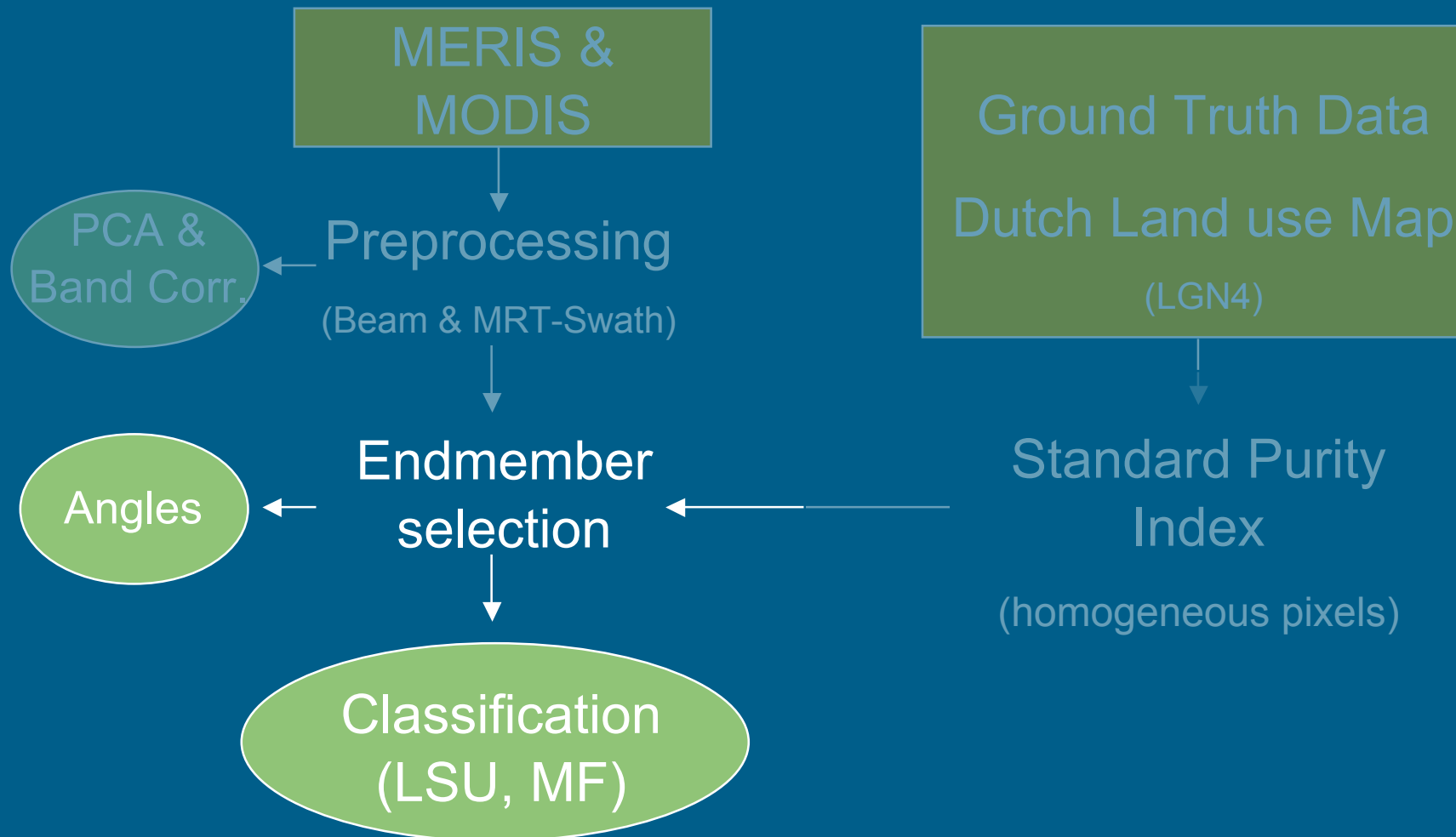
LGN 300m 4 classes



'Pure' Pixels

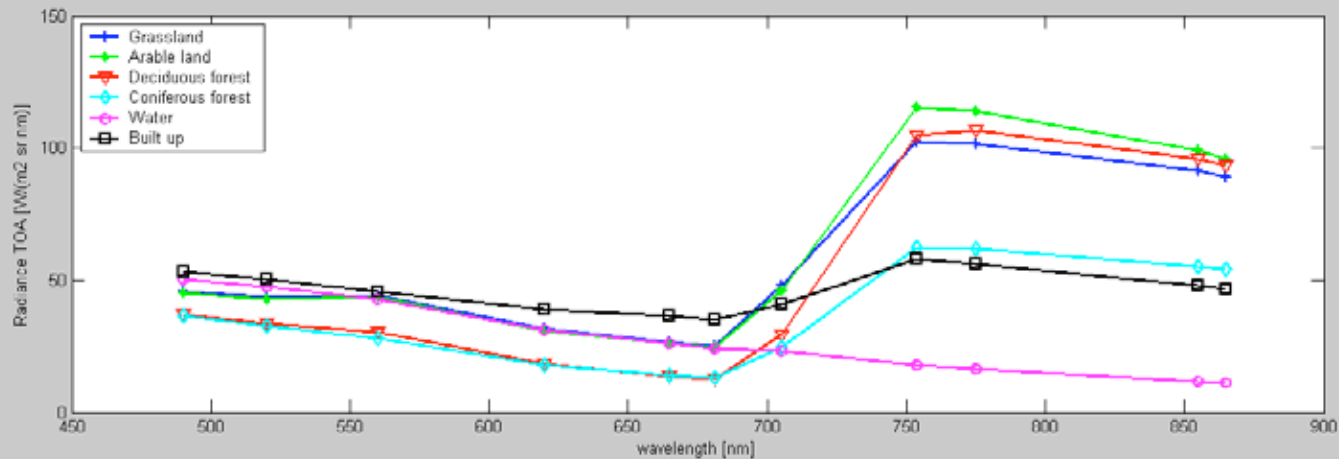


General Methodology

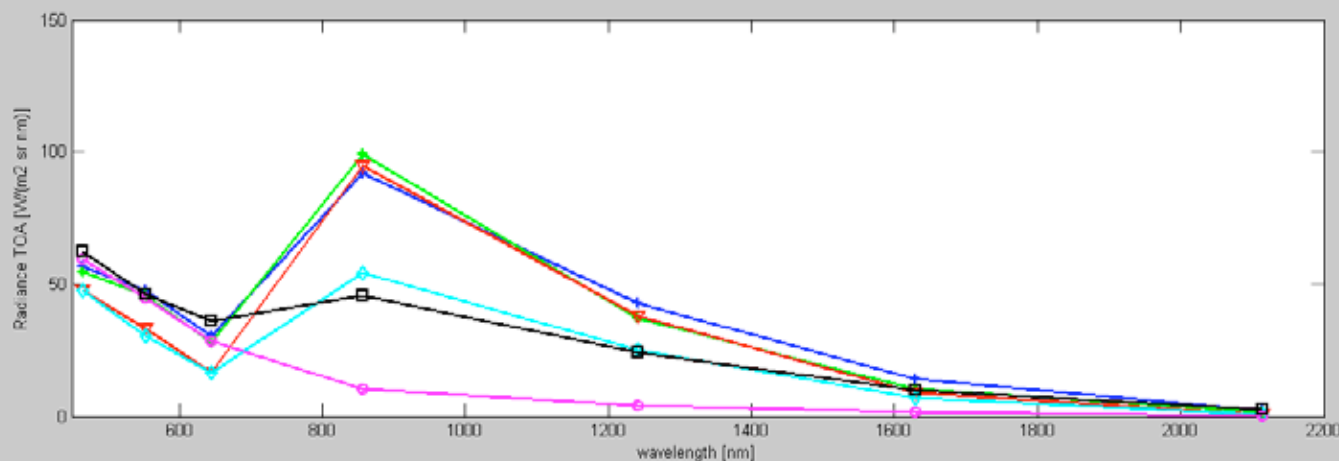


Results: Spectral Signatures of 6 endmembers

MERIS

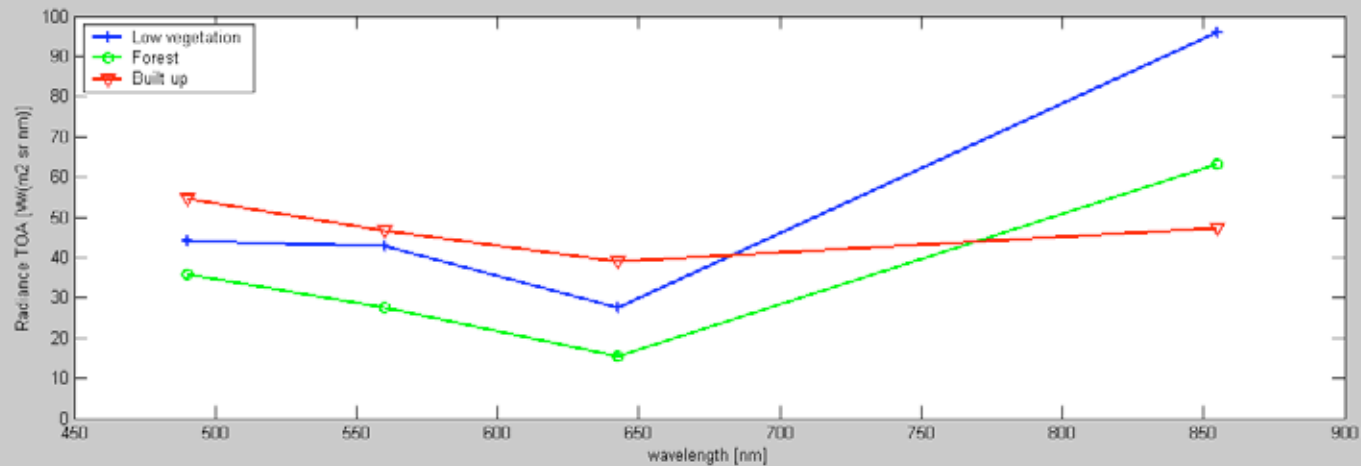


MODIS

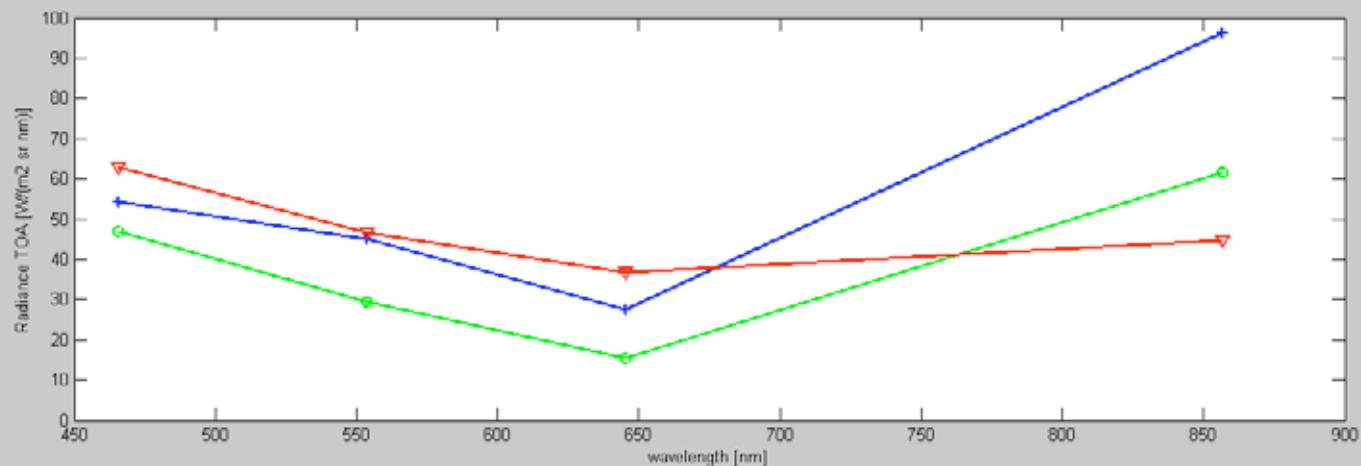


Results: Spectral Signatures of 3 endmembers

MERIS



MODIS



Results: Endmembers' Angles

$$\theta = \cos^{-1} \left[\frac{\int S_1(\lambda) S_2(\lambda) d\lambda}{\left[\int S_1(\lambda) d\lambda \right]^{1/2} \left[\int S_2(\lambda) d\lambda \right]^{1/2}} \right]^*$$

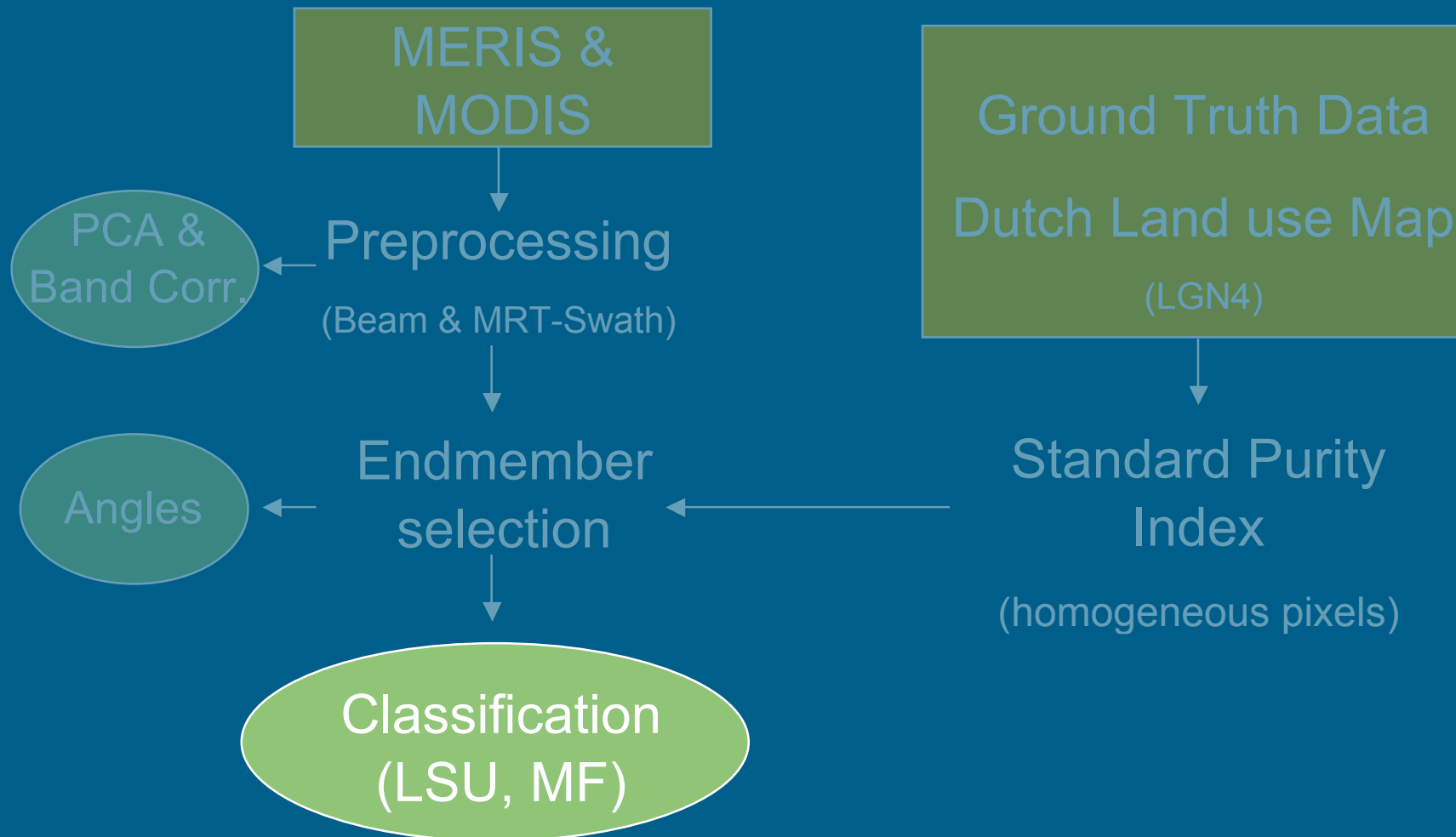
	Low vegetation	Forest	Built up
Low vegetation	--		
Forest	MODIS	--	
Built up	MERIS	MERIS	--

3 classes

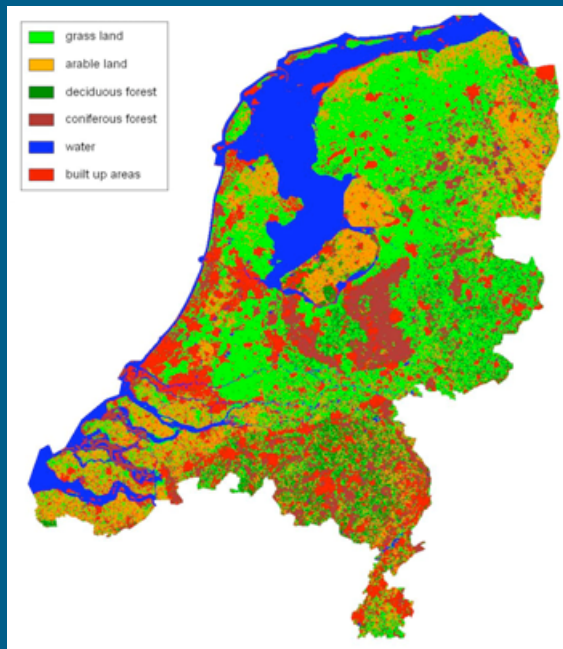
	Grassland	Arable land	Deciduous forest	Coniferous forest	Water	Built up
Grassland	--					
Arable land	MODIS	--				
Deciduous forest	MODIS	MERIS	--			
Coniferous forest	MODIS	MODIS	MODIS	--		
Water	MERIS	MERIS	MERIS	MERIS	--	
Built up	MODIS	MODIS	MERIS	MERIS	MERIS	--

6 classes

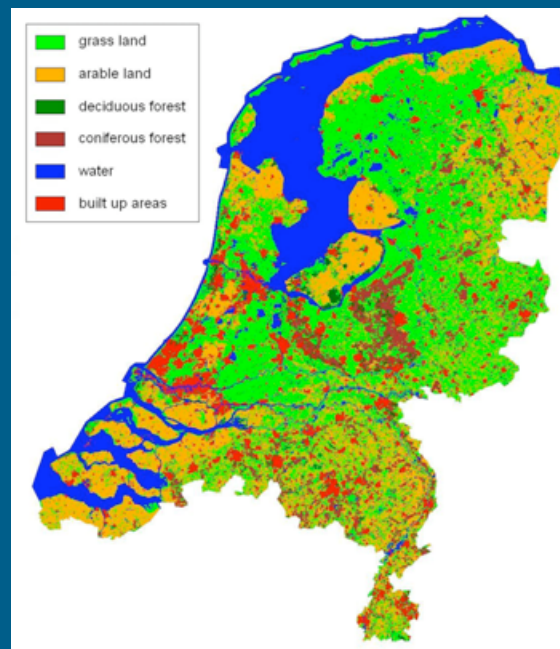
General Methodology



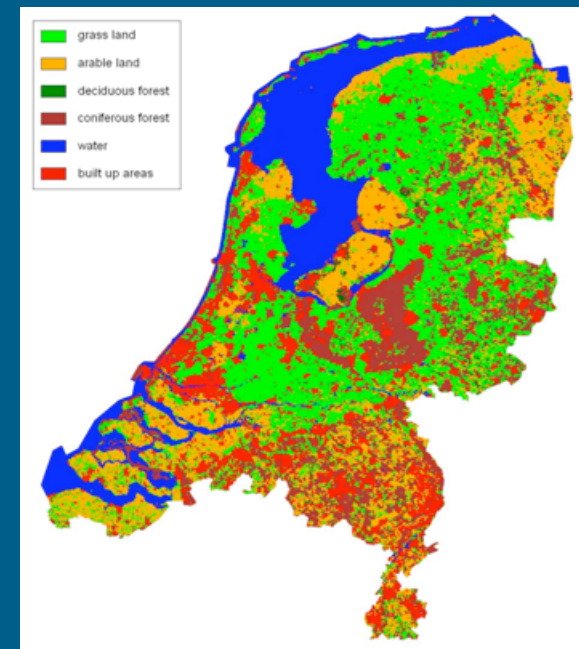
Results: Unmixed images MF 6 classes



MERIS



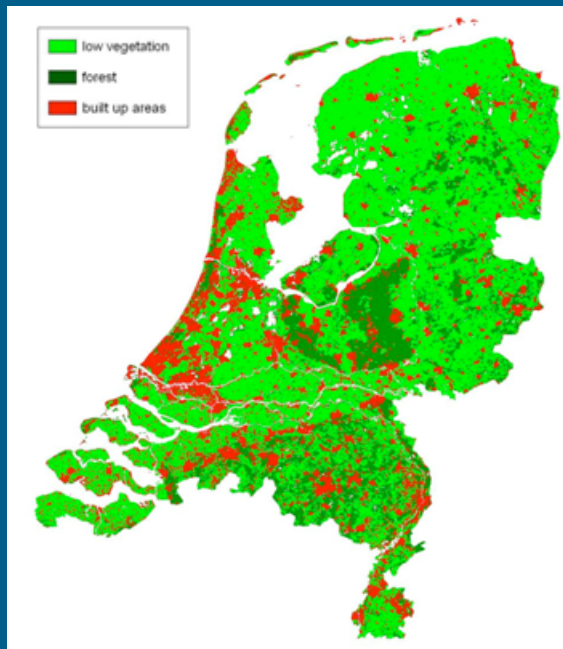
LGN



MODIS



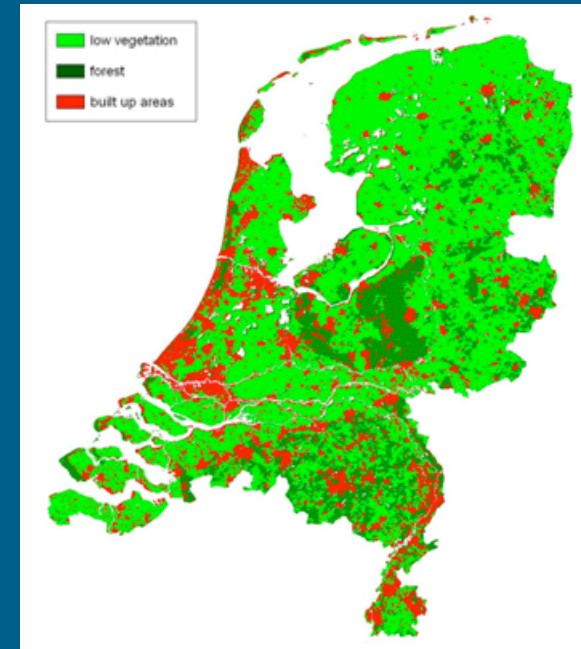
Results: Unmixed images MF 3 classes



MERIS



LGN



MODIS



Results: Quantification

Overall Accuracy (%)

	MERIS		MODIS	
	LSU	MF	LSU	MF
6 classes	57.08	60.25	40.58	61.29
3 classes	82.54	76.61	82.35	78.47

LSU: Linear Spectral Unmixing

MF: Matched Filtering

Conclusions and Recommendations

- Geometric and radiometric properties both of MERIS and MODIS seem OK.
- Both instruments showed a good performance for classifying land use in The Netherlands.
 - MERIS is slightly better when working with LSU
 - MODIS is slightly better when working with MF
- Combined use of MERIS and MODIS (Hierarchical schemes) could lead to an improved classification accuracy



Outlook

- Multitemporal classifications and the use of other classifiers (e.g. DT or Fuzzy) will be investigated in the near future.

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Thank you for your attention!

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